

# Mushroom Bodies Regulate Habit Formation in *Drosophila*

Björn Brembs<sup>1,\*</sup>

<sup>1</sup>Freie Universität Berlin, Institut für Biologie–Neurobiologie, Königin-Luise-Strasse 28-30, 14195 Berlin, Germany

## Summary

To make good decisions, we evaluate past choices to guide later decisions. In most situations, we have the opportunity to simultaneously learn about both the consequences of our choice (i.e., operantly) and the stimuli associated with correct or incorrect choices (i.e., classically) [1]. Interestingly, in many species, including humans, these learning processes occasionally lead to irrational decisions [2]. An extreme case is the habitual drug user consistently administering the drug despite the negative consequences, but we all have experience with our own, less severe habits. The standard animal model employs a combination of operant and classical learning components to bring about habit formation in rodents [3, 4]. After extended training, these animals will press a lever even if the outcome associated with lever-pressing is no longer desired [5]. In this study, experiments with wild-type and transgenic flies revealed that a prominent insect neuropil, the mushroom bodies (MBs), regulates habit formation in flies by inhibiting the operant learning system when a predictive stimulus is present. This inhibition enables generalization of the classical memory and prevents premature habit formation. Extended training in wild-type flies produced a phenocopy of MB-impaired flies, such that generalization was abolished and goal-directed actions were transformed into habitual responses.

## Results

A tethered fruit fly, *Drosophila*, in the absence of sensory information, continuously changes its choice of flight direction [6]. Much as humans learn about the consequences of their actions, the fly's choices can be modulated by learning about the consequences of such decisions as when and where to turn (i.e., operant learning [7]). Procedurally, the task is not significantly altered by adding predictive stimuli to this task such that one (e.g., blue coloration of the environment) indicates which turning maneuvers (e.g., left turning) are punished with heat and the other (e.g., green coloration) indicates which decisions (e.g., right turning) are not punished; the decisions are still followed by the same consequences. However, this helpful indication of correct and incorrect choices drastically alters the biological processes underlying the task. Without the help of the colors, the flies require protein kinase C function, but not the *rutabaga*-encoded type I adenylyl cyclase, to learn to make the correct choice; with the colors, the results are reversed [1]. In order to further investigate this dominant effect of the classical colors on operant learning, wild-type and transgenic flies were first trained

in situations with both operant and classical components present and were then tested for each component individually (Figure 1).

Given the dominance of the colors in this paradigm, it may not come as a surprise that in a test without heat, after 8 min of such composite training, wild-type flies did not reveal any preference for left- or right-turning maneuvers if the helpful color filters were removed (Figure 2A; i.e., the isolated operant component, situation 2 in Figure 1). Apparently, the colors inhibit operant learning. Why would the flies not learn an important predictor of punishment such as their own behavior? One hypothesis is that operant learning might lead to behavioral modifications, which in turn could potentially interfere with generalization of the classical color memory. Sensorimotor learning interfering with behavioral flexibility ("habit interference") is a well-known phenomenon [8], and the balance between interference and transfer/generalization is a popular research topic [9]. We tested for the generalization of the classical memory by measuring color preference in a situation where straight flight (as opposed to constant turning) was required to reliably avoid the previously punished color (i.e., situation 3 in Figure 1, previously described in [10]; see [Supplemental Experimental Procedures](#) available online for details). After 8 min of composite training, wild-type flies successfully avoided the punished color via this orthogonal behavior (Figure 2A), after a brief reminder training [10]. A commonly used experimental procedure to induce sensorimotor learning in other animals is overtraining [3, 4, 8]. According to the hypothesis above that learning of the operant behavior in flies may be analogous to sensorimotor learning leading to habit formation in mammals, extended training in flies should overcome the inhibition of operant learning and lead to a failure to generalize the isolated classical memory to the novel behavior. Consistent with this hypothesis, flies that were trained with equivalent operant and classical predictors for twice the regular amount of time showed significant performance indexes (PIs) in the control and in the operant test and no significant score in the generalization test (Figure 2B). Observing the behavior of the flies, it was noticeable that, after extended training, some flies seemed to generate larger turning maneuvers toward the previously unpunished direction, compared with more symmetrical maneuvers from flies exposed to the regular amount of training (Figure 2C). A quantitative evaluation of the behavioral data tended to confirm the qualitative observations, but the number of animals was too low to reach statistical significance (data not shown). Taken together, these results indicate that adjusting to the novel situation after extended composite training is difficult enough to disrupt performance in the generalization task (habit interference). Similar to a rodent pressing a lever for an aversive stimulus [2–4], the fly, also only after extended training, keeps generating behaviors that interfere with avoiding the previously punished color.

In order to elucidate the neuronal substrates mediating these processes, specific neuronal ensembles in the fly's brain were silenced. Because previous evidence pointed toward the MBs being involved in specific generalization processes [11–14], this neuropil was targeted with the UAS-GAL4 system to block synaptic output by expressing the bacterial tetanus

\*Correspondence: [bjoern@brembs.net](mailto:bjoern@brembs.net)

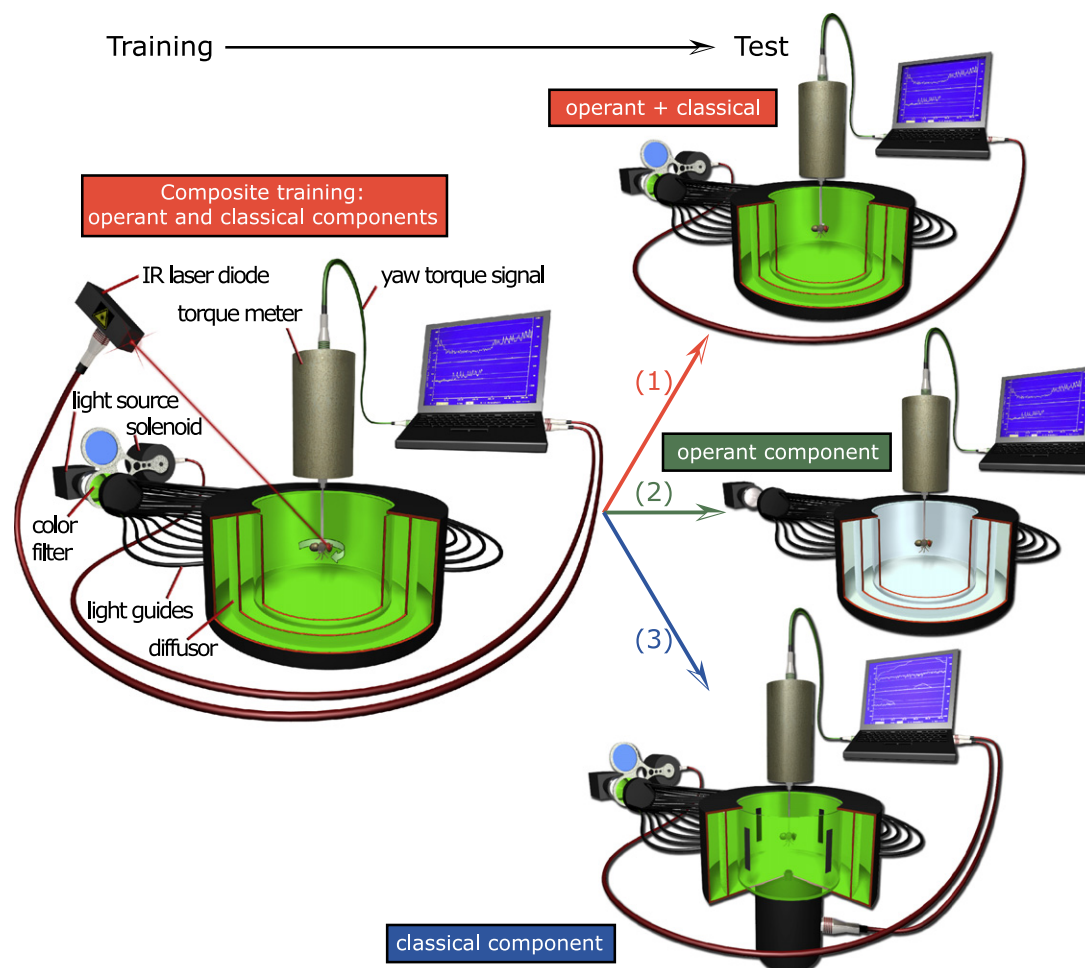
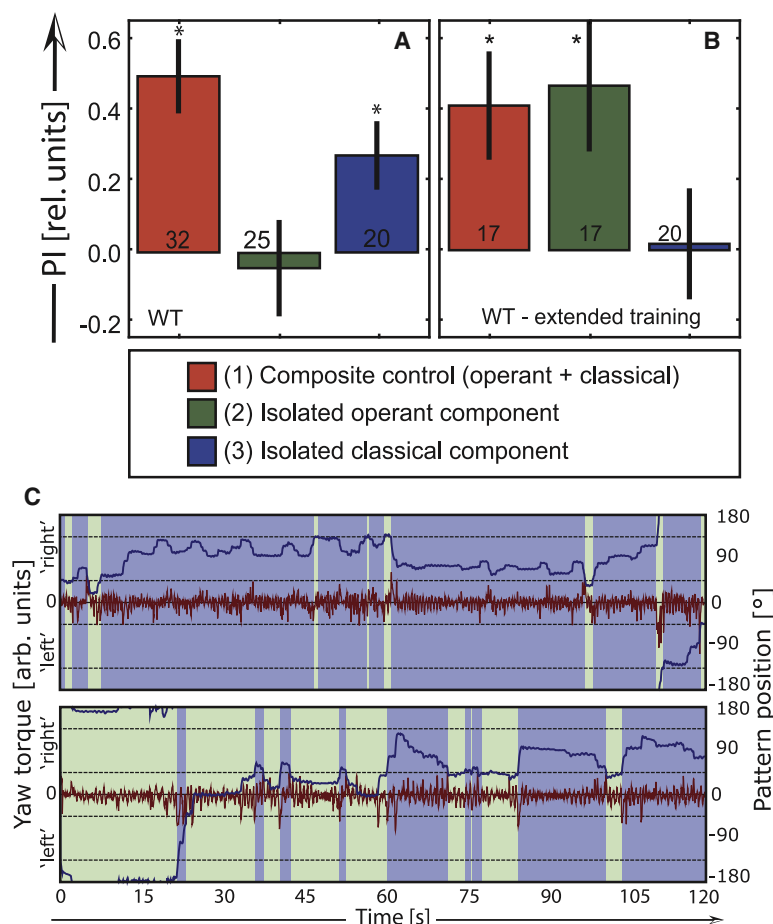


Figure 1. Experimental Design

During training, heat is used to simultaneously condition flies both to avoid turning to one direction (right or left; operant component) and one of two colors (blue or green, classical component). In a subsequent test without heat, the flies' spontaneous preference is recorded. One group of flies is tested in the same situation as during training (1). A second group of flies is tested for the operant component in isolation by removing the classical component (2). A third group of flies is tested for the classical component by replacing the operant behavior controlling the colors with a novel behavior (see [Supplemental Experimental Procedures](#) and [27] for details). The red (operant + classical), green (operant component) and blue (classical component) color scheme applies to all subsequent figures.

toxin light chain [15]. The first P[GAL4] driver line was MB247, because this line has already seen widespread use as an MB-specific driver line [11–14]. MB247 drives expression in about 1600 of the ~2000 Kenyon cells in all parts of the MB, except the prime lobes, and in some neurons of the central complex [16, 17]. The heterozygous control crosses of driver and effector strains with Canton S wild-type strains reproduced wild-type behavior (Figure 3A). Flies with impaired MB function can learn both the colors and how to modulate their turning movements [12, 18]. Confirming these previous results, flies with tetanus toxin expression driven by line MB247 could master the composite learning task composed of these two predictors (Figure 3B, situation 1). However, in a phenocopy of the wild-type flies after extended training, flies with such blocked MB output did not generalize the classical memory to a novel behavior and showed significant operant learning already after the regular 8 min of training (Figure 3B, situations 3 and 2, respectively). Thus, with such manipulated MB function, flies appear to form habits prematurely.

Flies in which the P[GAL4] line c205 drives expression of a constitutively active G-Protein are defective in visual pattern discrimination learning [19]. Constitutive expression of tetanus toxin in the F5 neurons in the fan-shaped body of the central complex via the line c205 confirmed that the effects of tetanus toxin expression were specific to the MB: in contrast to the MB247 flies, these flies behaved similarly to wild-type and genetic control flies (Figure 3C). In order to investigate which of the MB lobes are responsible for the inhibition of operant learning in such composite situations, transgenic flies with the P[GAL4] driver line 17D, which drives toxin expression mainly in the MB  $\alpha$  and  $\beta$  lobes (core and surface) but not in the  $\gamma$  lobes [11, 16], were subjected to the same procedure. These flies show the same pattern of PIs as the MB247 flies: significant PIs in the control and in the purely operant test and no significant score in the generalization test (Figure 3D), conclusively tying the inhibition of the operant component to MB neurons. Moreover, we can tentatively conclude that the MB  $\gamma$  lobes are probably not involved in this process.



**Figure 2.** The Hierarchical Interaction between Operant and Classical Learning Systems Is Brought about by an Inhibition of Operant Learning

(A) Standard 8 min training in wild-type (WT) flies. Whereas there is significant composite learning (red:  $t_{31} = 5.1$ ,  $p < 0.001$ ), the score for the isolated operant component does not reach significance (green:  $t_{24} = -0.3$ ,  $p < 0.8$ ; not even after a 60 s reminder training, data not shown). However, there is significant transfer of the classical color memory to a novel behavior (blue:  $t_{19} = 3.1$ ,  $p < 0.01$ ) indicates successful generalization.

(B) Extended 16 min training reverses the scores for the isolated components. The longer training duration does not lead to an overtraining decrement ( $t_{16} = 2.8$ ,  $p < 0.013$ ). Testing for the operant component shows a release from the inhibition of operant learning ( $t_{16} = 2.6$ ,  $p < 0.02$ ). Without inhibition of the operant system, the flies are unable to generalize ( $t_{19} = 0.1$ ,  $p < 0.91$ ).

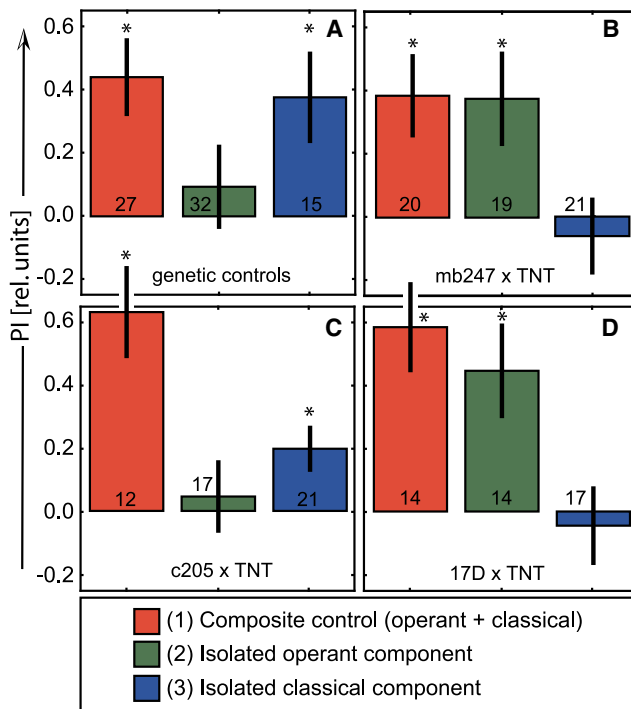
(C) Example raw data traces from the generalization test (situation 3 in Figure 1). Data from two wild-type flies during the test period depicted in (A) and (B). The red traces depict the turning maneuvers (yaw torque) used to change flight direction (blue trace, pattern position) and hence coloration of the environment (background color of the graph). Upper traces: fly after 8 min of training to turn right and avoid green color (pooled data in A). Lower traces: fly after 16 min of training to turn left and avoid blue color (pooled data in B). Whereas the fly trained for the regular amount of time shows symmetrical turning maneuvers, the fly trained for an extended period of time shows left turning yaw torque spikes (discrete turning maneuvers) of uniformly larger amplitude than its right turning yaw torque spikes (traces enlarged in Figure S1). Numbers at bars: number of animals. \*Significant difference from zero. Error bars are SEM.

## Discussion

Spontaneous behavior has clear fitness benefits [6]. However, spontaneous behavioral variation may reduce efficiency by introducing mistakes. The success of an animal thus depends on finding the right balance between efficient exploitation of known resources through routine behavior and flexible exploration of possible new resources through novel behaviors (the exploitation-exploration dilemma [20, 21]). In a new situation, such as the operant paradigm used here, the animal explores the environment via spontaneous behaviors [6]. It learns about the stimuli in this environment and how they relate to each other primarily by engaging the classical learning system [1]. During this phase, the classical learning system inhibits the operant system via the MB, preventing direct modification of the behavior of the animal and keeping the memory flexible (Figures 2 and 3). After extended periods of time in this situation, the MB-mediated inhibition is overcome and the behavior is modified by the operant learning system, which may improve efficiency but also leads to inflexibility (Figure 2B). The current data allow establishing a mechanistic model of how operant and classical learning systems may interact in composite learning situations and which biological substrates mediate these processes (Figure 4). In this view, the Rutabaga adenylyl cyclase-dependent classical learning system inhibits the protein kinase C-dependent operant learning system via the MB. The operant learning system facilitates classical learning via still unknown, non-MB pathways (data not shown and [10]). This interaction leads to efficient learning, enables

generalization, and prevents premature habit formation. In flies, it is not yet known whether the two learning systems are also separable anatomically. It is tempting to speculate that the interactions between the two learning systems are part of the mechanism achieving the balance between exploration and exploitation. In this hypothesis, the MBs provide the checks and balances to ensure that habits are formed only if their efficiency outweighs their disadvantage of being inflexible.

Such an MB function would be distinct from the one that the MBs are known to serve in olfactory classical conditioning. The current consensus is that the memory trace formed during this kind of learning lies within the MB Kenyon cells [22–24]. This is clearly not the case for visual learning, where the MBs are not essential [12, 18]. Instead, specific features of the conditioned stimulus in visual learning appear to reside in distinct layers of the fan-shaped body of the central complex [19]. For visual learning, the MBs appear to keep classical memories flexible for use when the fly's situation changes. If the fly's sensory situation changes, this feature supports context generalization [11, 12] and protects against sensory conflict [13, 14]. If the fly's behavioral situation changes, this feature supports the form of generalization described here. From these accumulating recent results, it appears that the inhibitory function of the MB may be much more pervasive than previously thought. It is a tantalizing finding for all *Drosophila* learning and memory research that overtrained wild-type flies behave indistinguishably from flies with blocked MB output: whenever the neural substrate of a learning task is studied, the question of whether the training regime constitutes



**Figure 3. The Mushroom Body  $\alpha$  and  $\beta$  Lobes, but Not the  $\gamma$  Lobes, Are Necessary for Inhibition of the Operant Component and Generalization of Classical Memory**

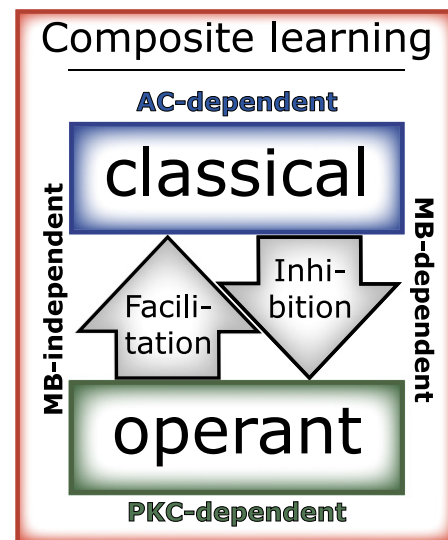
(A) The genetic control flies (the two heterozygote strains did not differ and were pooled) reproduce the wild-type results: significant composite learning ( $t_{26} = 3.8$ ,  $p < 0.001$ ), inhibition of the operant component ( $t_{31} = 0.7$ ,  $p < 0.5$ ), and successful generalization of the isolated classical component ( $t_{14} = 2.7$ ,  $p < 0.05$ ).

(B) Flies with blocked MB output constitute a phenocopy of the wild-type flies with extended training, already after 8 min of training. They perform well in composite learning (red:  $t_{19} = 3.1$ ,  $p < 0.01$ ), but do not inhibit the operant component during composite training (green:  $t_{18} = 2.6$ ,  $p < 0.05$ ). Without inhibition of the operant system, these transgenic flies are unable to generalize the isolated classical component to a novel behavior (blue:  $t_{20} = -0.5$ ,  $p < 0.6$ ).

(C) Specificity of the MB effects is provided by expressing TNT in the fan-shaped body. These flies behave as wild-type and control heterozygote flies with significant composite learning ( $t_{11} = 4.3$ ,  $p < 0.002$ ) and inhibition of the operant system ( $t_{16} = 0.4$ ,  $p < 0.7$ ), which in turn allows for a successful generalization of the classical component to a novel behavior ( $t_{20} = 2.7$ ,  $p < 0.014$ ).

(D) Flies with blocked output only from the  $\alpha$  and  $\beta$  lobes of the MB mimic the flies expressing tetanus toxin in all MB lobes. They perform well in composite learning ( $t_{13} = 4.3$ ,  $p < 0.001$ ), do not inhibit the operant system ( $t_{13} = 3.1$ ,  $p < 0.01$ ), and do not generalize ( $t_{16} = -0.38$ ,  $p < 0.71$ ). Numbers at bars: number of animals. \*Significant difference from zero. Error bars are SEM.

overtraining must now also be considered. This is reminiscent of vertebrate experiments, where the dorsal striatum and the hippocampus are viewed as competing learning systems with the dorsal striatum involved in skill-learning and the hippocampus in fact-learning [4, 25]. Short training is primarily processed by the hippocampus, whereas prolonged training recruits the dorsal striatum. Interestingly, if the prelimbic medial prefrontal cortex is lesioned in rats, even short training leads to habit formation [26], reminiscent of the flies with blocked MB output. To my knowledge, habit formation has never been shown in any invertebrate model system before. This discovery entails that models for addiction and other compulsive disorders can now also be developed in the fly.



**Figure 4. Hypothetical Model of Composite Learning Consisting of Two Components with Reciprocal, Hierarchical Interactions**

In learning situations where the animal has the possibility to simultaneously learn about relationships between stimuli in the world and about the consequences of its own behavior, two learning systems can be engaged. One learning system learns about the world (classical learning system), and the other system learns to modify behavior (operant learning system). The AC-dependent classical learning system inhibits PKC-dependent operant learning via the mushroom bodies (MBs). Operant behavior controlling predictive stimuli facilitates learning about these stimuli by the classical learning system via unknown, non-mushroom-body pathways. These interactions lead to efficient learning, generalization and prevent premature habit-formation. AC, adenylyl cyclase; PKC, protein kinase C.

Combining the tools developed in the approach of localizing memory traces [17, 19] with the experimental separation of operant and classical learning components [1], *Drosophila* has now entered the stage where we can start to unravel not only where memories are stored but also how and where basic neural subsystems interact to accomplish efficient learning in more ethologically relevant situations, without compromising generalization or prematurely engaging habit formation. Research on *Drosophila* has provided key insights into mechanisms of classical learning that are evolutionary conserved. The utility of this model system has now been extended to the study of complex learning situations comprising multiple, interacting learning systems on the behavioral, circuit, and genetic level. These studies expand a growing body of literature that simultaneously engaged memory systems can act both cooperatively and antagonistically.

#### Supplemental Data

Supplemental Data include Supplemental Experimental Procedures and one figure and can be found with this article online at [http://www.cell.com/current-biology/supplemental/S0960-9822\(09\)01253-6](http://www.cell.com/current-biology/supplemental/S0960-9822(09)01253-6).

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## Supplemental Data

### Mushroom Bodies Regulate Habit

#### Formation in *Drosophila*

Björn Brembs

#### Supplemental Experimental Procedures

The method of fly culture and preparation, the apparatus and the main features of the experimental design have been published as an open access video publication in order to enhance comprehension of these complex procedures [1].

#### Fly Strains

Because of the effects of MB function on context generalization [2, 3], we expressed the catalytic subunit of bacterial tetanus toxin (TNT) to block synaptic output from the MB. Despite some technical issues which have been raised recently [4, 5], we favored TNT over the temperature-sensitive *shibire* effector, because of the heat punishment in our paradigm. We use the trans-heterozygote offspring from the driver (MB247) and the effector strain (UAS<sub>GAL4</sub>-TNT) for our studies as described previously [2, 6, 7]. The heterozygote offspring from crossing driver and reporter strain, respectively, to Canton-S wild-type flies served as genetic controls for these experiments. In addition to the MB247 line we also used the line 17D which only expresses in the  $\alpha$  and  $\beta$  lobes, but not in the  $\gamma$  lobes [8]. Any shared effects between the two crosses can therefore be attributed to the overlapping expression pattern in the MB between the two driver lines. To test for the specificity of the effects in the MB GAL4 lines, we tested a non-MB line, c205, which drives TNT expression in the F5 neurons of the fan-shaped body [9]. As both wild-type *Berlin* and Canton-S strains behave indistinguishably from each other in learning experiments such as those presented here, some wild-type experiments were also performed with the *Berlin* strain (marked WT).

#### Fly Preparation and Apparatus

Flies were kept on standard fly medium at 25°C and staged for behavioral experiments [1]. After gluing each 24-48h old female fly with head and thorax to a triangle-shaped copper hook, the animals were kept individually overnight in small moist chambers with sucrose [1]. During the experiment, the torque meter measures a fly's angular momentum around its vertical body axis, caused by intended flight maneuvers. The fly is tethered in the center of a cylindrical panorama (arena, diameter 58mm), which is homogeneously illuminated from behind (Fig. 1). For green and blue illumination of the arena, the light is passed through monochromatic broad band Kodak Wratten gelatin filters (#47 and #99, respectively). Filters can be exchanged by a fast solenoid within 0.1s. Alternatively, the arena is illuminated throughout the experiment with 'daylight' by passing it through a blue-green filter (Rosco "surfblue" No. 5433). The transmission spectrum of the Rosco filter used in this study constitutes an intermediate between the Kodak blue and green filters [10]. Punishment is achieved by applying heat from an adjustable infrared laser (825 nm,

150 mW), directed from behind and above onto the fly's head and thorax [1]. The laser beam is pulsed (approx. 200ms pulse width at ~4Hz) and its intensity reduced to assure the survival of the fly. The experiment is fully automated and computer controlled.

### **Experimental Design**

Each fly was used only once. The time-course of the experiment was divided into consecutive periods of 2 minutes duration. Depending on whether heat may be applied during such a period, it is termed a training period (heating possible) or a test period (heat off). Standard experiments consisted of two pre-test periods (labeled  $PI_1$  and  $PI_2$ ) 4 training periods ( $PI_3$ ,  $PI_4$ ,  $PI_6$  and  $PI_7$ ) and three memory test periods ( $PI_5$ ,  $PI_8$  and  $PI_9$ ). Only in experiments testing the generalization of the classical memory,  $PI_8$  was a 60s familiarization training and  $PI_9$  was scored as memory test. For experiments with extended training, the experimental time course was essentially repeated such that in total four additional training periods ( $PI_9$ ,  $PI_{10}$ ,  $PI_{12}$ ,  $PI_{13}$ ) followed training- $PI_7$ , as well as five test periods ( $PI_8$ ,  $PI_{11}$ ,  $PI_{14}$ ,  $PI_{15}$ ). Only in experiments testing the generalization of the classical memory,  $PI_{14}$  was a 60s familiarization training and  $PI_{15}$  was scored as memory test. Depicted are always the  $PI$ 's of the first two minutes after the last training period. All animals were trained with operant and classical predictors as described before [11, 12]. In brief, the fly's spontaneous yaw torque range was divided into a 'left' and 'right' domain, approximately corresponding to either left or right turns [13]. Heat punishment and arena coloration were made contingent on this behavior such that, e.g., left turning lead to green arena illumination and heat on, whereas right turning lead to blue arena illumination and heat off. Punishment of yaw torque domains/colors was always counterbalanced. For the standard duration experiments, this situation lasted until  $PI_7$ , the final training period. Only in experiments with extended training duration was this situation prolonged until  $PI_{13}$ . After the final training period, the animals were divided into three different groups. The three groups essentially follow the three experiments described before [11]. Group 1 (control) was tested in the composite situation without heat. Group 2 was tested without heat or colors for spontaneous choice of yaw torque domains (operant component). Group 3 was tested only for the color preference using a different behavior (classical component). This test with a different behavior was performed as described previously [12]. Briefly, the panorama of the fly is replaced with a new arena, containing four evenly spaced, identical vertical stripes. Each stripe denotes the center of a virtual  $90^\circ$  quadrant. A computer controlled electric motor rotates the arena such that its angular velocity is proportional to, but directed against the fly's yaw torque. The color of the illumination of the whole arena is changed whenever one of the virtual quadrant borders passes a point in front of the fly. During the 60s familiarization/reminder training, heat punishment is made contiguous with the color punished in the previous composite learning phase. During test, the heat is permanently switched off. Despite relying on yaw torque as the composite situation, this test for the generalization of the classical memory requires the animal to use a different motor output than was used during composite training. While during composite training the animal had to constantly turn in one direction to keep arena illumination constant, in this flight-simulator-like situation, the animal has to fly straight to accomplish the same effect. Thus, any operant component learned during composite training would interfere with generalization of the classical component.

## Data Evaluation

The color or yaw torque domain preference of individual flies is calculated as the performance index:  $PI = (t_a - t_b) / (t_a + t_b)$ . During training periods,  $t_b$  indicates the time the fly is exposed to the heat and  $t_a$  the time without heat. During tests,  $t_a$  and  $t_b$  refer to the times when the fly chose the formerly (or subsequently) unpunished or punished situation, respectively. Thus, a PI of 1 means the fly spent the entire period in the situation not associated with heat, whereas a PI of -1 indicates that the fly spent the entire period in the situation associated with heat. Accordingly, a PI of zero indicates that the fly distributed the time evenly between heated and non-heated situations.

## Statistics

Individual PIs were tested for significance using a t test for single means against zero, following previous studies [2, 3, 9, 10]. All data are expressed as means  $\pm$  SEM.

## Supplemental References

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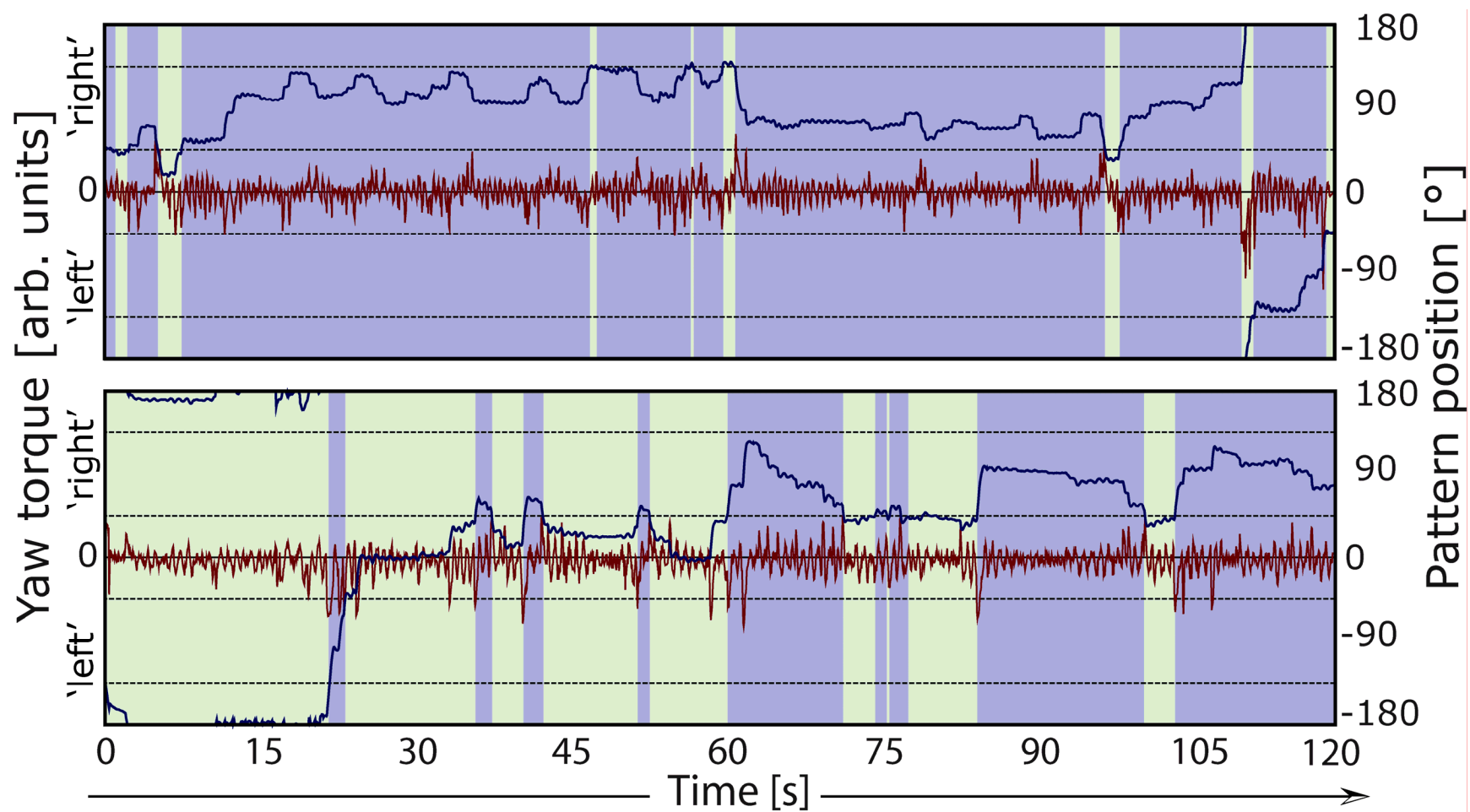


Figure S1. Expansion of the Example Traces in Figure 2C